



KVASER U100-X1

EAN: 73-30130-01266-0

The Kvaser U100-X1 is a robust, single-channel CAN/CAN FD to USB interface with reinforced galvanic isolation (tested according to EN 60335-1:2012 paragraph 13 with 5000 VAC rms applied for 60 seconds) that squarely addresses the needs of the evolving automotive development market. Fully compatible with J1939, CANopen, NMEA 2000® and DeviceNet, this is the first in a new range of interfaces that is also suited to rugged applications in marine, industrial, heavy duty vehicle and heavy industries.

Warranty

2-year warranty. See our General Conditions and Policies for details.

Support

Free support for all products by contacting support@kvaser.com.

Major Features

- Supports CAN FD, up to 8 Mbit/s (with correct physical layer implementation).
- Supports both 11-bit (CAN 2.0A) and 29-bit (CAN 2.0B active) identifiers.
- Lightweight, glass fibre reinforced polyamide housing, overmolded with TPE.
- J1939-13 Type II connector (other connectors available).
- Intelligent LED UI.
- Reinforced Galvanic Isolation. (Tested according EN 60335-1:2012 paragraph 13, 5000VAC rms applied for 60 seconds)
- 20000 msg/s, each timestamped with a resolution of 100 µs.
- Support for SocketCAN.
- Compatible with J1939, CANopen, NMEA 2000® and DeviceNet.
- Fully compatible with applications written for other Kvaser CAN hardware with Kvaser CANlib.

Technical Data

CAN Bit Rate	10 kbit/s to 1 Mbit/s
CAN FD	Yes
CAN FD Bit Rate	Up to 8 Mbit/s
CAN Channels	1
CAN Transceivers	ADM3055E
Casing Material	PA/TPE
Connector	J1939-13 Type II
Current Consumption	Typical 250 mA
Dimensions	38 x 128 x 26 mm
Galvanic Isolation	Yes, reinforced. Validated with 5000 VAC rms applied for 60 seconds.
IP Rating Housing	IP67
Operating Temperature Range	-40 °C to +85 °C
Timestamp Resolution	100 µs
Weight	167 g
Operating Systems	Windows, Linux

Software

Documentation, Kvaser CANlib SDK and drivers can be downloaded for free at www.kvaser.com/downloads.

Kvaser CANlib SDK is a free resource that includes everything you need to develop software for the Kvaser CAN interfaces. Includes full documentation and many program samples, written in C, C++, C#, Delphi, Visual Basic, Python and t programming language.

Kvaser CAN hardware is built around the same common software API. Applications developed using one device type will run without modification on other device types